

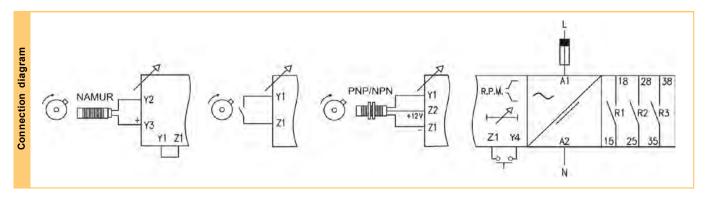
SHA





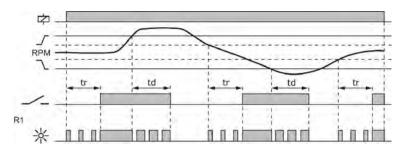
TACHOMETRIC RELAY

Function	Tachometric relay for general application. Control and visualization of the rotation speed of motors shafts, turbines, etc., speed control on conveyor belts, control the stop or break transmission chains or endless conveyor.				
Operating mode	Configurable by the user. Each relay is assigned with its own operating mode.				
Control of rotation speed	 Operating margin: 39999 rpm The device does not process impulses with a duration less than 1/8 of the full cycle. Operability for max. and/or min. rotation speed. In each case, detection and release is to be adjusted. Operability for minimum rotation speed and engine starting. You can control the motor start by using a push button between terminals Z1-Y4 (see example on page 2) 				
Timer	 Associable to the detection and/or release of any relay and to the engine startup. Adjustable from 0.01 s 999.9 h Repeating precision ± 30 ppm 				
Resolution	1 rpm				
Precision	1%				
Time of detection	3 flanks of the input signal plus 5 ms of the relay reaction.				
Types of rpm input signal	 Contact free potential: Y1 / Z1 Namur sensor: Y2 / Y3(+), link Y1/Z1 PNP / NPN sensor: Y1 / Z1(-) / Z2(+12VCC). Maximum 10 mA 				
Type of input of the engine startup	Contact free potential: Y4 / Z1 Only for the operability by minimum rotation speed in the engine startup.				
Visualization to read value	The read magnitud value is displayed by the status screen: ROTATION SPEED: rpm				
Output relay	From 1 to 3 independent relays, SPST NO. Three relays are supplied with the standard model.				
Output 4-20 mA	Assigned to the measure of the magnitude to be transmitted by the 4-20 mA current loop. It can coexist with the relays. Precision: 1% additional to the read value. This kind of output is optional.				
PC communication	It is possible establish different types of communication with a computer (see also the last page): - By telephone connector that incorporates standard device and programming interface CPBZ. - By a RS232 connection board (optional). - By a RS2485 connection and the SBAZ converter (optional).				



Control of maximum and minimum rotation speed

Settings available in the program 1 for relay R3. Parameters must be adapted to your installation.

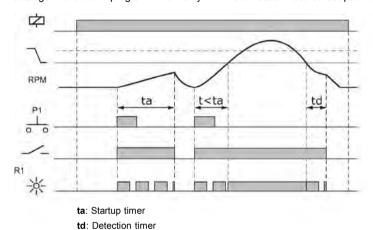


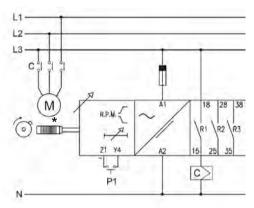
- td: Detection timer
- tr: Release timer

Control of minimum rotation speed and engine startup

At a minimum control rotation speed, the relay SHA requires that the motor runs at its rated speed to get an effective control. This application allows to assign a start timing during which inhibits the control of the rotational speed. It is essential to start the engine by a push button connected to terminals Z1-Y4.

Settings available in program 1 for relay R1. Parameters must be adapted to your installation.

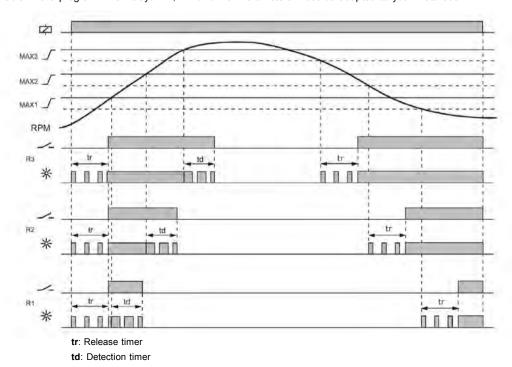


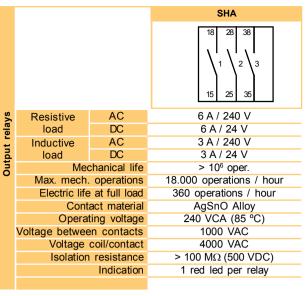


* See at page 1 the types of sensors that can be used in this device

Scaling control of maximum rotation speed

In this application there are controlled three different points of maximum rotation speed, assigning each one to a different relay. Settings available in the program 2 for relays R1, R2 and R3. Parameters must be adapted to your installation.





		SHA			
		AC	AC - DC		
Supply voltage		A2 I _N	= A1 A2 A2		
ᅙ	Supply voltage code	[024] [440]	[903]	[904]	
ď	Galvanic isolation	4000 V	2500 V		
0,	Frequency	50/60 Hz		-	
	Operating margins	+10% -15%	15-70 V	60-240 V	
	Consumption	2,5 VA	3,5 W	3,1 W	
	Startup time	75 ms		< 135 ms*	
	Reset	> 1 network cycle		ms*	
		and/or -30% of the	and/or -3	0% of the	
		nominal voltage		voltage	
	Indication	Gree	n led		
	* In the worst of the cases				

		200.17
	Voltage phase-neutral	300 V
	Overvoltage category	<u> </u>
	Shock voltage	4 kV
ta	Pollution degree	2 (EN61010)
data	Protection	IP 20
æ	Approx. weight	280 g
ī	Store temperature	-30+80°C
enviromental	Operating temperature	-20+50°C
ī.	Humidity	< 95% HR
2	Housing	Cycoloy - Light grey
	Leds window	Lexan - Transparent
and	Buttons, connector, clamp	Technyl - Dark blue
a	Connector's terminals	Brass
Š	Screws torque	0,8 Nm
tructive	Dessigned and manufacture	ed under EEC normative.

Supply voltage input Options selection Screens selection Change of values Parts of the equipment Text edition LCD screen Validation (Signaling of the supply voltage and status Connector of the relays Contacts of communication the relays (under)

Directives referred:
Electromagnetic compatibility: EMC 2004/108/EEC.
Low voltage: LVD 2006/95/EEC.
Hazardous substances: 2011/65/EEC

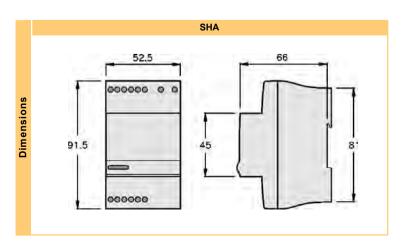
Plastics: UL 91 V0

Order code

		Control - Interface	Number of relays	Type of relays	Communication	Version	Supply	Range
SHA	9 - Q -	With display Default languages:	0 - No relays 3 - 3 relays	0 - No relays A - SPST NO	0 - No bus 4 - 4-20 mA 3 - RS232 8 - RS485	0099	[024] 24 VAC [110] 110125 VAC [230] 220240 VAC [400] 380415 VAC [440] 440 VAC [903] 1570 VAC/DC [904] 60240 VAC/DC	[10K] 39999 rpm
	U -	Without display Communication RS232 / RS485	(By default, 3)	(By default, A)	(By default, 0)	(By default, 00)		

To compose a reference, select one option of each one of the columns. Example: SHA9 3A000 230 10K

Communication (According options)					
Standard	RS232	RS485	4-20 mA		
Code 0	Code 3	Code 8	Code 4		
CCPBZ — CCPBZ	NC U RXD U TXD U XC	GND A B NC	1 2 3 12.30 V=		



	GENERAL CHARACTERISTICS OF THE DIGITAL CONTROL RELAYS
User's manual	For a wide knowledgment of the options offered by the digital control relays, the own User's Manual for each model must be read. Although an issue is given with every purchased device, a copy can be donwloaded in our web site (www.disibeint.com).
How to programm	The digital control relays can be indistinctly programmed either with the buttons placed in the front of the housing or with a personal computer. Please refer at the end of this page to learn more about the PC programming alternative.
Types of screens	Status: They show the actual values of the magnitudes controlled by the relay. User: Where the user can write a customized text to help to the relay identification. Options: For accessing to the menus for the options selection. Informatives for values: They show the information of the different set parameters. Change of value: For modifying the values of the different values. Screens menus: Group of screens related under the same concept and that can contain whichever type of the screens previously described.
Interactive menus	1 /
Changing values	The screens for changing the values contain the margins betwen such value can be adjusted. These margins can depend of other options and this is because different margins could be displayed according to other previous relations.
User's programms	Provided by factory two programs with options and pre-configured settings for quick start-up team. In most cases, these parameters should be tweaked to suit the characteristics of each installation. The user can create your own program and store it on your computer.
Display lighting	longer than 30 seconds, the light turns off. In order to turn the light on, it is enough to press any button.
Value added	 Four languages available in each relay Graphic bar for the intuitive visualization of the displayed value Historical control of the maximum values obtained by the relay Screen's refresh selectable between 1 and 8 times per second Possibility of locking the keyboard to avoid any undesired modification Complementary timing functions

PC COMMUNICATION

deCom

- \cdot Communication and programming software for the digital control relays.
- It allows the interactivity between the different types of communication: through the CBPZ interface, RS232 or RS485.
- \cdot It displays the complete data related to the relay, gruoped by concepts and easing the intuitive programming.
- It has control tools to do not exceed the operating margins of each model according to its range.
- · It is provided with templates to facilitate the programming of each model.
- · It allows to store the own settings.

Windows XP operative system (.NET Framework required).









